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 Robotics with the BOE Shield – RightServoStayStill

 Transmit the center or stay still signal on pin 12 for center adjustment.

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#include <Servo.h>                           // Include servo library

Servo servoRight;                            // Declare right servo

void setup()                                 // Built-in initialization block

{

  servoRight.attach(12);                     // Attach right signal to pin 12

  servoRight.writeMicroseconds(1500);        // 1.5 ms stay still signal

}

void loop()                                  // Main loop auto-repeats

{                                            // Empty, nothing needs repeating

}